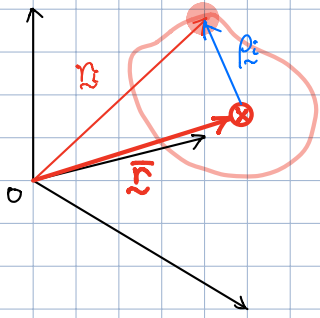


3. Impulse & Momentum

(a) Linear Momentum



1. one particle : $\underline{G}_i = m_i \underline{v}_i = m_i \dot{\underline{r}}_i$

2. System of particles : $\underline{G} = \sum \underline{G}_i = \sum m_i \dot{\underline{r}}_i$ ← $\underline{r}_i = \underline{r} + \underline{\rho}_i$

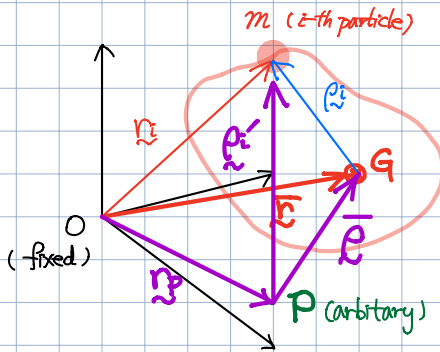
$$= \sum m_i (\dot{\underline{r}} + \dot{\underline{\rho}}_i)$$

$$= \sum m_i \dot{\underline{r}} + \frac{d}{dt} (\sum m_i \underline{\rho}_i)$$

← $\sum m_i \underline{r}_i = (\sum m_i) \underline{r}$
 $\sum m_i (\underline{r}_i - \underline{r})$
 $= \sum m_i \underline{\rho}_i = 0$

$\underline{G} = M \dot{\underline{r}}$

(b) Angular Momentum



★점이나 관측한 Δ 에 대한 각운동량

★	Δ	Answer
O	O	$H_O = \underline{r}_i \times m_i \dot{\underline{r}}_i$
O	G	$H_G = \underline{\rho}_i \times m_i \dot{\underline{r}}_i$
G	G	$(H_G)_{rel G} = \underline{\rho}_i \times m_i \dot{\underline{\rho}}_i$
P	G	$(H_G)_{rel P} = \underline{\rho}_i \times m_i \dot{\underline{\rho}}_i'$

1. (O점이나 관측한) O점에 대한 각운동량

$$H_O = \sum_i (\underline{r}_i \times m_i \dot{\underline{r}}_i)$$

$$\dot{H}_O = \sum (\cancel{\dot{\underline{r}}_i \times m_i \underline{r}_i} + \underline{r}_i \times m_i \ddot{\underline{r}}_i)$$

← $\dot{\underline{r}} \parallel \underline{r}$ $= \underline{F}_i$

$$= \sum \underline{r}_i \times \underline{F}_i = \sum \underline{M}_i$$

고정점 O에 대한 Resulting Moment

System O점이 대한 각운동량 변화율과 같다.

2. CM에 대한 각운동량

$$(H_G)_{rel G} = \sum \underline{\rho}_i \times m_i \dot{\underline{\rho}}_i = \sum \underline{\rho}_i \times m_i (\dot{\underline{r}}_i - \dot{\underline{r}})$$

$$= \sum \underline{\rho}_i \times m_i \dot{\underline{r}}_i - (\sum \underline{\rho}_i \times m_i \dot{\underline{r}})$$

← $\alpha \underline{u} \times \beta \underline{u} = 0$ ($\underline{u} \times \underline{u} = 0$)
 $= \beta \underline{u} \times \alpha \underline{u}$

$$= \sum \underline{\rho}_i \times m_i \dot{\underline{r}}_i - (\sum m_i \underline{\rho}_i) \times \dot{\underline{r}}$$

$$= \sum \underline{\rho}_i \times m_i \dot{\underline{r}}_i$$

$$= H_G \text{ (O점이나 관측한 G에 대한 각운동량)}$$

$$(H_G)_{rel P} = \sum \underline{\rho}_i \times m_i \dot{\underline{\rho}}_i' = \sum \underline{\rho}_i \times m_i (\dot{\underline{r}}_i - \dot{\underline{r}}_P)$$

$$= \sum \underline{\rho}_i \times m_i \dot{\underline{r}}_i - \sum \underline{\rho}_i \times m_i \dot{\underline{r}}_P$$

$$= \sum \underline{\rho}_i \times m_i \dot{\underline{r}}_i - (\sum m_i \underline{\rho}_i) \times \dot{\underline{r}}_P$$

$$= H_G$$

O, G, P 점이나 관측한 G점에 대한 각운동량 같은 동일!

$$H_G = \sum \underline{\rho}_i \times m_i \dot{\underline{r}}_i$$

$$= \sum \underline{\rho}_i \times \underline{f}_i = \sum \underline{M}_G$$

$$H_G = \sum \underline{\rho}_i \times m_i \dot{\underline{r}}_i$$

$$H_G = \sum \underline{\rho}_i \times m_i \dot{\underline{r}}_i + \sum \underline{\rho}_i \times m_i \dot{\underline{r}}_i$$

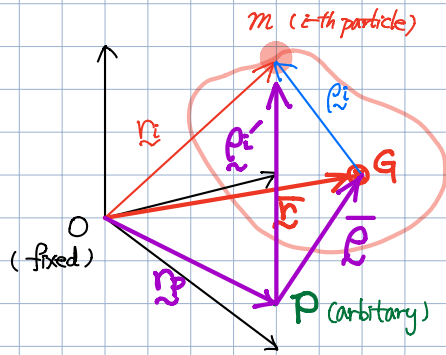
← $\sum m_i \underline{\rho}_i \times \dot{\underline{r}}_i$

$$= \sum \underline{\rho}_i \times m_i (\dot{\underline{r}} + \dot{\underline{\rho}}_i)$$

$$= \sum \underline{\rho}_i \times m_i \dot{\underline{r}} + \sum \underline{\rho}_i \times m_i \dot{\underline{\rho}}_i$$

← $\sum m_i \underline{\rho}_i \times \dot{\underline{r}}$ $\underline{\rho}_i \parallel \underline{\rho}_i$

★ 정점에 관한 Δ 에 대한 각운동량



★	Δ	Answer
O	O	$H_O = \underline{r_i} \times m_i \dot{\underline{r_i}}$
O	Q	$H_Q = \underline{p_i} \times m_i \dot{\underline{r_i}}$
Q	Q	$(H_Q)_{relQ} = \underline{p_i} \times m_i \dot{\underline{p_i}}$
P	Q	$(H_Q)_{relP} = \underline{p_i} \times m_i \dot{\underline{p_i}}$
O	P	$H_P = \underline{r_i'} \times m_i \dot{\underline{r_i}}$
P	P	$(H_P)_{relP} = \underline{p_i'} \times m_i \dot{\underline{p_i'}}$

3. p점에 대한 각운동량

$$\begin{aligned}
 H_P &= \sum \underline{p_i'} \times m_i \dot{\underline{r_i}} = \sum (\underline{p} + \underline{p_i}) \times m_i \dot{\underline{r_i}} \\
 &= \sum \underline{p} \times m_i \dot{\underline{r_i}} + \sum \underline{p_i} \times m_i \dot{\underline{r_i}} \quad \leftarrow \sum m_i \dot{\underline{r_i}} = \sum m_i (\dot{\underline{x}} + \dot{\underline{p_i}}) \\
 &= H_Q + \sum \underline{p} \times M \dot{\underline{r}}
 \end{aligned}$$

$$\begin{aligned}
 \sum m_i \dot{\underline{r_i}} &= \sum m_i (\dot{\underline{x}} + \dot{\underline{p_i}}) \\
 &= \sum m_i \dot{\underline{x}} + \sum m_i \dot{\underline{p_i}} \\
 &= (\sum m_i) \dot{\underline{x}} \\
 &= M \dot{\underline{x}}
 \end{aligned}$$

$$\begin{aligned}
 (H_P)_{relP} &= \sum \underline{p_i'} \times m_i \dot{\underline{p_i'}} = \sum (\underline{p} + \underline{p_i}) \times m_i \dot{\underline{p_i'}} \\
 &= \sum \underline{p} \times m_i \dot{\underline{p_i'}} + \sum \underline{p_i} \times m_i \dot{\underline{p_i'}} \\
 &= \underline{p} \times \sum m_i (\dot{\underline{p_i}} + \dot{\underline{p_i}}) \\
 &= \underline{p} \times (\sum m_i \dot{\underline{p_i}} + \sum m_i \dot{\underline{p_i}}) \\
 &= \underline{p} \times M \dot{\underline{p}}
 \end{aligned}$$

$$(H_P)_{relP} = H_Q + \underline{p} \times M \dot{\underline{r}}$$

$$\begin{aligned}
 H_Q &= (H_P)_{relP} - \underline{p} \times M \dot{\underline{r}} \quad \leftarrow \frac{d}{dt} (\underline{p} \times M \dot{\underline{r}}) \\
 &= \dot{\underline{p}} \times M \dot{\underline{r}} + \underline{p} \times M \ddot{\underline{r}}
 \end{aligned}$$

$$H_Q = \dot{\underline{p}} \times M \dot{\underline{r}}$$

$$\begin{aligned}
 &= (H_Q)_{relP} + \underline{p} \times M \ddot{\underline{r}} \\
 &= H_Q + \underline{p} \times M \ddot{\underline{r}}
 \end{aligned}$$

$$\sum \underline{M} \dot{\underline{p}} = \sum \underline{M} \dot{\underline{p}} + \underline{p} \times \sum \underline{F}$$

$$\begin{aligned}
 &= \dot{\underline{p}} \times M \dot{\underline{r}} + \underline{p} \times \sum \underline{F} \\
 &= (H_P)_{relP} - \underline{p} \times M \ddot{\underline{r}} + \underline{p} \times M \ddot{\underline{r}}
 \end{aligned}$$

$$\begin{aligned}
 \therefore \sum \underline{M} \dot{\underline{p}} &= (H_P)_{relP} + \underline{p} \times M (\ddot{\underline{r}} - \ddot{\underline{r}}) \\
 &= \ddot{\underline{r}}
 \end{aligned}$$

$$\therefore \sum \underline{M} \dot{\underline{p}} = (H_P)_{relP} + \underline{p} \times M \ddot{\underline{r}}$$

The resultants of the external forces acting on the system expressed in terms of the resultant forces ($= \sum \underline{F}$) through Q and the corresponding couple $\sum \underline{M} \dot{\underline{p}}$.

O, Q, P 정점에 대한 Q 정점에 대한 각운동량 같은데요!

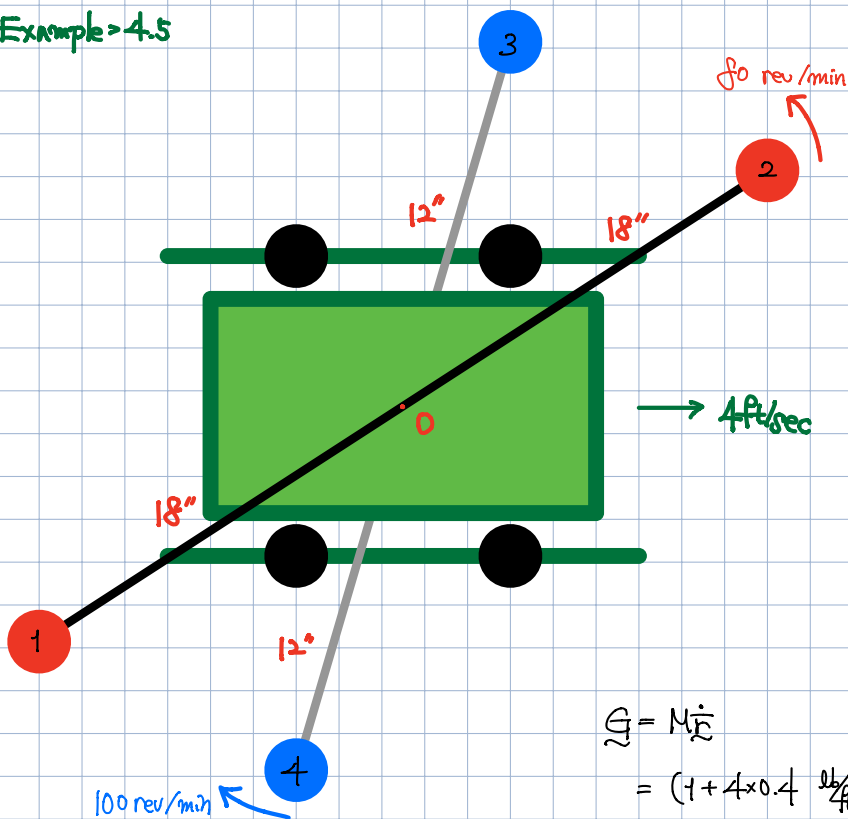
$$\begin{aligned}
 H_Q &= \sum \underline{p_i} \times m_i \dot{\underline{r_i}} \\
 H_Q &= \sum \underline{p_i} \times m_i \dot{\underline{r_i}} + \sum \underline{p_i} \times m_i \dot{\underline{r_i}} \quad \leftarrow \sum m_i \dot{\underline{r_i}} \times \underline{r_i} \\
 &= \sum \underline{p_i} \times m_i (\dot{\underline{x}} + \dot{\underline{p_i}}) \\
 &= \sum \underline{p_i} \times m_i \dot{\underline{x}} + \sum \underline{p_i} \times m_i \dot{\underline{p_i}} \\
 &= \sum m_i \dot{\underline{x}} \times \underline{p_i} + \sum m_i \dot{\underline{p_i}} \times \underline{p_i} \\
 H_Q &= \sum \underline{p_i} \times m_i \dot{\underline{r_i}} = \sum \underline{p_i} \times \dot{\underline{r_i}} = \sum \underline{M} \dot{\underline{p}}
 \end{aligned}$$

$$\therefore \Sigma \dot{M}_p = (\dot{H}_p)_{relp} + \bar{\rho} \times M \ddot{r}_p$$

$$\Sigma \dot{M}_p = (\dot{H}_p)_{relp}$$

$$\text{if } \begin{cases} \textcircled{1} \ddot{r}_p = 0 & (\text{관성 좌표계}) \rightarrow \Sigma \dot{M}_O = \dot{H}_O \\ \textcircled{2} \bar{\rho} = 0 & (p \text{는 } G \text{의 중심}) \rightarrow \Sigma \dot{M}_G = \dot{H}_G \\ \textcircled{3} \bar{\rho} \parallel \ddot{r}_p & \rightarrow \Sigma \dot{M}_p = (\dot{H}_p)_{relp} \end{cases}$$

Example > 4.5



32.2 lb carriage A moves with a speed of 4 ft/sec and carries two assemblies of balls and light rods which rotate about a shaft at O.

Each of the four balls weighs 3.22 lb

Determine $\dot{G}$, $\dot{H}_O = ?$

$$\dot{G} = M \dot{\bar{r}}$$

$$\dot{H}_G = \Sigma \bar{\rho}_i \times m_i \dot{r}_i$$

$$\dot{G} = M \dot{\bar{r}}$$

$$= (1 + 4 \times 0.4 \frac{16}{12}) \cdot (4 \frac{ft}{s})$$

$$= 5.6 \frac{lb \cdot ft}{sec} \quad \text{Ans.}$$

$$\dot{H}_O = \dot{H}_G = \Sigma \bar{\rho}_i \times m_i \dot{r}_i$$

$$= \Sigma \rho_i m_i \dot{r}_i \sin 90^\circ$$

$$= \left\{ (18 \cancel{in}) \frac{16 \cancel{in}}{12 \cancel{in}} \cdot (0.1 \frac{lb}{ft}) \cdot (12.57 \frac{ft}{s}) \right\} \times 2$$

$$+ \left\{ (12 \cancel{in}) \cdot (0.1) \cdot (-10.47) \right\} \times 2$$

$$= 1.676 \frac{ft \cdot lb}{sec} \quad \text{Ans.}$$