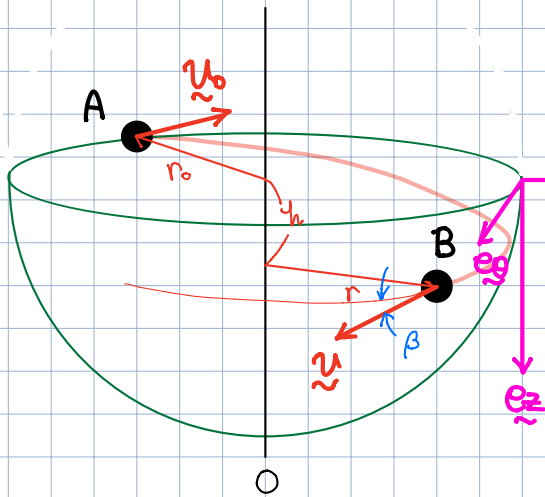


Example 3.27

A small mass particle is given an initial velocity u_0 at r_0 .

As the particle slides past point B, a distance h below A and a distance r from the vertical centerline, its velocity u makes angle β with the horizontal tangent to the bowl through B.

Determine β .



1. Coordinate $\rightarrow (r, \theta, z)$ coord.

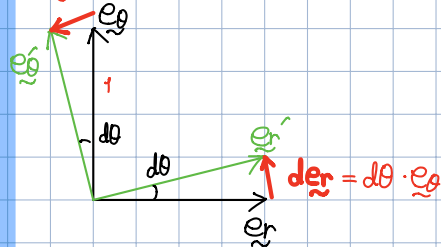
2. Vectors

$$\underline{r} = r \underline{e}_r + z \underline{k}$$

$$\begin{aligned} \dot{\underline{r}} &= \dot{r} \underline{e}_r + r \dot{\underline{e}}_r + \dot{z} \underline{k} + z \dot{\underline{k}} \\ &= \dot{r} \underline{e}_r + r \dot{\underline{e}}_\theta + \dot{z} \underline{k} \\ &= \dot{r} \underline{e}_r + r \dot{\theta} \underline{e}_\theta + \dot{z} \underline{k} \end{aligned}$$

$$\begin{aligned} \ddot{\underline{r}} &= \ddot{r} \underline{e}_r + \dot{r} \dot{\underline{e}}_r + \dot{r} \dot{\underline{e}}_\theta + r \ddot{\underline{e}}_\theta + r \dot{\theta} \dot{\underline{e}}_\theta + \ddot{z} \underline{k} + z \dot{\underline{k}} \\ &= \ddot{r} \underline{e}_r + 2\dot{r} \dot{\theta} \underline{e}_\theta + r \ddot{\theta} \underline{e}_\theta - r \dot{\theta}^2 \underline{e}_r + \ddot{z} \underline{k} \\ &= (\ddot{r} - r \dot{\theta}^2) \underline{e}_r + (2\dot{r} \dot{\theta} + r \ddot{\theta}) \underline{e}_\theta + \ddot{z} \underline{k} \end{aligned}$$

$$d\underline{e}_\theta = d\theta (-\underline{e}_r)$$



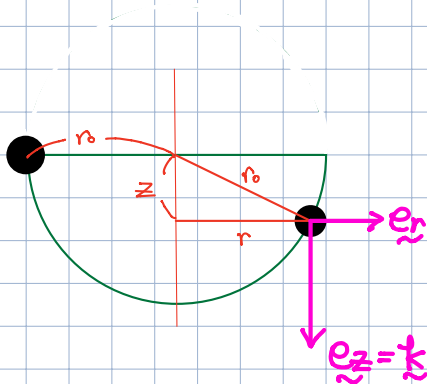
$$\frac{d\underline{e}_r}{dt} = d\theta \frac{d\underline{e}_\theta}{dt}$$

$$\dot{\underline{e}}_r = \dot{\theta} \underline{e}_\theta$$

$$\frac{d\underline{e}_\theta}{dt} = d\theta \frac{d(-\underline{e}_r)}{dt}$$

$$\dot{\underline{e}}_\theta = -\dot{\theta} \underline{e}_r$$

3. Constraints



$$r^2 + z^2 = r_0^2$$

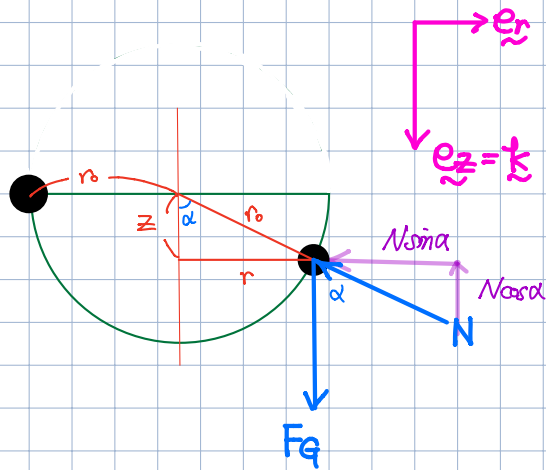
$$2r\dot{r} + 2z\dot{z} = 2r_0\dot{r}_0$$

$$r\dot{r} + z\dot{z} = 0$$

$$r\ddot{r} + r\dot{r}^2 + z\ddot{z} + z\dot{z}^2 = 0$$

constrained: $r_0^2 = r^2 + z^2$

4. Free Body Diagram



$$N = (N \sin \alpha) (-\underline{e}_r) + (N \cos \alpha) (-\underline{k})$$

$$= -N \sin \alpha \underline{e}_r - N \cos \alpha \underline{k}$$

$$F_g = (mg) \underline{k}$$

5. Equation of Motion

$$\Sigma \underline{F} = m \underline{\ddot{r}} \quad \leftarrow \quad \underline{\ddot{r}} = (\ddot{r} - r\dot{\theta}^2) \underline{e}_r + (2\dot{r}\dot{\theta} + r\ddot{\theta}) \underline{e}_\theta + \ddot{z} \underline{k}$$

$$= m(\ddot{r} - r\dot{\theta}^2) \underline{e}_r + m(2\dot{r}\dot{\theta} + r\ddot{\theta}) \underline{e}_\theta + m\ddot{z} \underline{k}$$

$$= -N \sin \alpha \underline{e}_r - N \cos \alpha \underline{k} + mg \underline{k}$$

$$\begin{cases} 1. & m(\ddot{r} - r\dot{\theta}^2) = -N \sin \alpha \quad \leftarrow \sin \alpha = \frac{r}{r_0} \\ & \quad \quad \quad = -N \cdot \frac{r}{r_0} \\ 2. & m\ddot{z} = mg - N \cos \alpha = mg - N \frac{z}{r_0} \\ 3. & m(2\dot{r}\dot{\theta} + r\ddot{\theta}) = 0 \\ 4. & \text{constrained: } r^2 = z^2 + r_0^2 \end{cases}$$

$\leftarrow \text{unknown} = 4\pi$
 $N = 4\pi$

$$\text{from 3: } \frac{1}{r} \cdot \frac{d}{dt}(r^2\dot{\theta}) = 0 \quad \leftarrow \frac{d}{dt}(r^2\dot{\theta}) = 2r\dot{\theta} + r^2\ddot{\theta}$$

$$\underline{r^2\dot{\theta} = \text{constant}}$$

6. Calculation

integration of E.O.M. with respect to path.

$$\int_A^B m \underline{\ddot{r}} \cdot d\underline{r} = \int_A^B \underline{F}_g \cdot d\underline{r} + \int_A^B \underline{N} \cdot d\underline{r} \quad \leftarrow \underline{F}_g = mg \underline{k}$$

$$d\underline{r} = dr \underline{e}_r + r d\theta \underline{e}_\theta + dz \underline{k}$$

$$= \int_A^B (mg \underline{k}) \cdot (dr \underline{e}_r + r d\theta \underline{e}_\theta + dz \underline{k})$$

$$= \int_A^B mg dz = mgh$$

$$* \quad v = \frac{ds}{dt} \quad a = \frac{dv}{dt}$$

$$\downarrow \quad \leftarrow \quad dt = \frac{dv}{a}$$

$$v = \frac{ds}{(dv/a)} = a \frac{ds}{dv}$$

$$\therefore a ds = v dv$$

$$\ddot{r} dr = v dv$$

$$\therefore \int_A^B m \ddot{r} dr = \int_A^B m v dv$$

$$= \frac{1}{2} m (v_B^2 - v_A^2)$$

$$\frac{1}{2} m v_B^2 - \frac{1}{2} m v_A^2 = m g h$$

$$v_B = \sqrt{2gh + v_A^2}$$

$$\hat{e}_\theta \cdot \hat{u}_B = |\hat{e}_\theta| |\hat{u}_B| \cos \beta$$

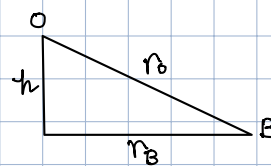
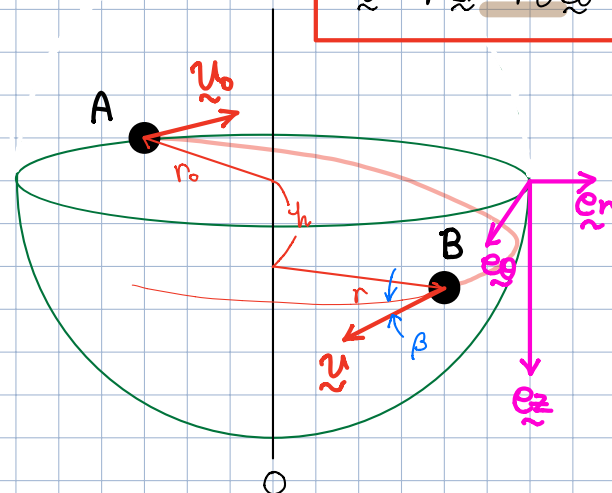
$$= 1 \cdot \sqrt{2gh + v_A^2} \cos \beta$$

$$= (\dot{r})_B$$

$$* \quad r^2 \dot{\theta} = \text{constant}$$

$$(r^2 \dot{\theta})_B = (r^2 \dot{\theta})_A = (r^2 \dot{\theta})_A$$

$$(\dot{r})_B = \frac{1}{r_B} (r_A^2 \dot{\theta})_A = \frac{1}{r_B} (r_A v_A) \leftarrow v_A = r_A \dot{\theta}$$



$$\sqrt{2gh + v_A^2} \cos \beta = \frac{1}{r_B} (r_A v_A)$$

$$\cos \beta = \frac{\frac{1}{r_B} (r_A v_A)}{\sqrt{2gh + v_A^2}} \leftarrow r_B = \sqrt{r_0^2 - h^2}$$

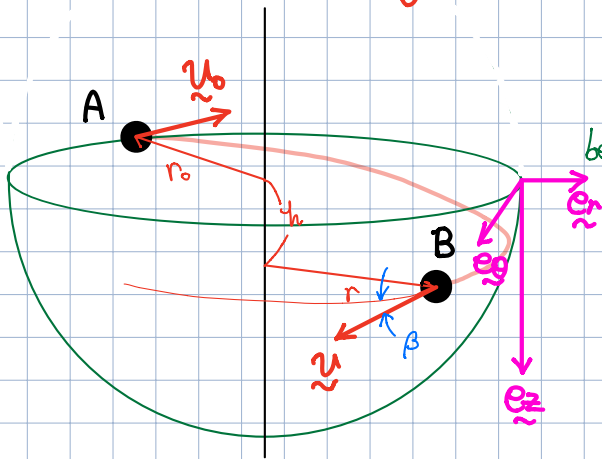
$$= \frac{r_0 v_A}{\sqrt{r_0^2 - h^2} \cdot \sqrt{2gh + v_A^2}}$$

$$= \sqrt{r_0^2 (1 - \frac{h^2}{r_0^2})} = \sqrt{v_A^2 (1 + \frac{2gh}{v_A^2})}$$

$$\beta = \cos^{-1} \left(\frac{1}{\sqrt{1 - \frac{h^2}{r_0^2}} \cdot \sqrt{v_0^2 (1 + \frac{2gh}{v_0^2})}} \right) \leftarrow v_A = v_0$$

Ans.

Example 3.27 (Energy)



A small mass particle is given an initial velocity u_0 at r_0 .

As the particle slides past point B, a distance h below A and a distance r from the vertical centerline, its velocity u makes angle β with the horizontal tangent to the bowl through B.

Determine β .

* $(H_0)_1 = (H_0)_2$ conservation of angular momentum

$$\begin{aligned} H_0 &= \mathbf{r} \times m\mathbf{u} \\ &= r m u \sin 90^\circ \\ &= r m u \end{aligned}$$

$$(H_0)_1 = r_0 m u_0 \longrightarrow m u_0 r_0 = m r u \cos \beta$$

$$\therefore u_0 r_0 = \sqrt{u_0^2 + 2gh} \cdot \sqrt{r_0^2 - h^2} \cdot \cos \beta$$

$$(H_0)_2 = r m u \cos \beta$$

* $E_1 = E_2$ conservation of energy

$$T_1 + V_1 = T_2 + V_2$$

$$\frac{1}{2} m u_0^2 + mgh = \frac{1}{2} m u^2 + 0$$

$$\therefore u = \sqrt{u_0^2 + 2gh}$$

$$* r^2 = r_0^2 - h^2$$

$$\therefore \beta = \cos^{-1} \left(\frac{1}{\sqrt{1 + \frac{2gh}{u_0^2}} \cdot \sqrt{1 - \left(\frac{h}{r_0}\right)^2}} \right)$$

Ans.