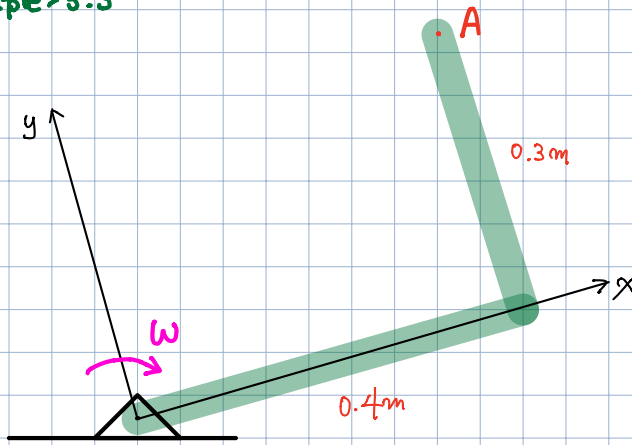


Example 5.3



The right-angle bar rotates clockwise with an angular velocity which is decreasing at the rate of 4 rad/s^2

Determine velocity & acceleration of point A when $\omega = 2 \text{ rad/s}$

$$\underline{v} = \underline{\omega} \times \underline{r}$$

$$\underline{a}_n = \underline{\omega} \times (\underline{\omega} \times \underline{r})$$

$$\underline{a}_t = \underline{\alpha} \times \underline{r}$$

$$\underline{a} = \underline{a}_n + \underline{a}_t$$

rotates clockwise : $\underline{\omega} = -2\hat{k} \text{ rad/s}$

$$\underline{\alpha} = 4\hat{k} \text{ rad/s}^2$$

$$\underline{r}_A = 0.4\hat{i} + 0.3\hat{j}$$

$$\underline{v}_A = \underline{\omega} \times \underline{r} = (-2\hat{k}) \times (0.4\hat{i} + 0.3\hat{j}) = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 0 & 0 & -2 \\ 0.4 & 0.3 & 0 \end{vmatrix} = 0.6\hat{i} - 0.8\hat{j} \text{ m/s}$$

Ans.

$$\underline{a} = \underline{a}_n + \underline{a}_t$$

$$\underline{a}_n = \underline{\omega} \times (\underline{\omega} \times \underline{r}) = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 0 & 0 & -2 \\ 0.6 & -0.8 & 0 \end{vmatrix} = -1.6\hat{i} - 1.2\hat{j}$$

$$\underline{a}_t = \underline{\alpha} \times \underline{r} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 0 & 0 & 4 \\ 0.4 & 0.3 & 0 \end{vmatrix} = -1.2\hat{i} + 1.6\hat{j}$$

$$\therefore \underline{a} = -2.8\hat{i} + 0.4\hat{j}$$

Ans.

$$|\underline{a}| = \sqrt{2.8^2 + 0.4^2} = 2.83 \text{ m/s}^2$$

Ans.

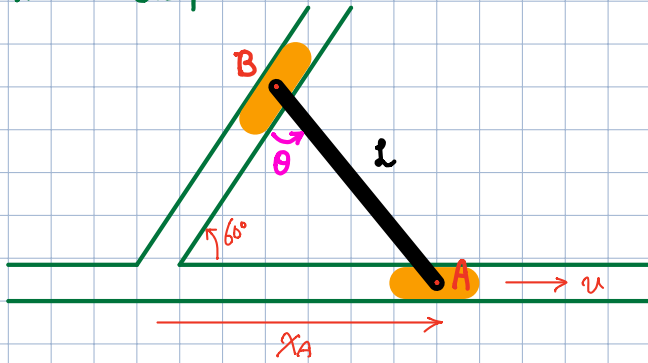
$$|\underline{v}| = \sqrt{0.6^2 + 0.8^2} = 1 \text{ m/s}$$

Ans.

Absolute Motion

The geometric relations $\rightarrow$ define the configuration of the body.

Problem 5.34



Determine the angular velocity ω of the bar AB in terms of $\dot{x}_A$

$$\frac{\dot{x}_A}{\sin \theta} = \frac{l}{\sin 60^\circ} \rightarrow \dot{x}_A = \frac{l \sin \theta}{\sin 60^\circ} = \frac{2}{\sqrt{3}} l \sin \theta$$

$$\dot{x}_A = \frac{2}{\sqrt{3}} l \cos \theta \cdot \dot{\theta} \rightarrow \omega$$

$$\dot{\theta} = \omega = \frac{\sqrt{3} v}{2 l \cos \theta} = \frac{\sqrt{3} v}{2 l} \cdot \frac{1}{\sqrt{1 - \frac{3}{4} \frac{\dot{x}_A^2}{v^2}}}$$

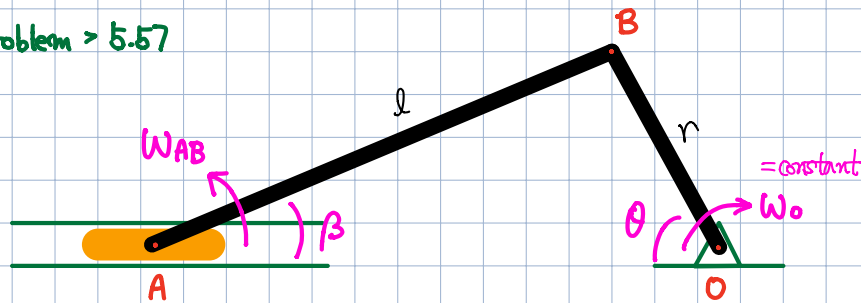
Ans.

$$\sin \theta = \sin 60^\circ \cdot \dot{x}_A / l$$
$$= \frac{\sqrt{3}}{2} \dot{x}_A / l$$

$$\sin^2 \theta + \cos^2 \theta = 1$$

$$\cos \theta = \sqrt{1 - \sin^2 \theta} = \sqrt{1 - \frac{3}{4} \frac{\dot{x}_A^2}{v^2}}$$

Problem > 5.57



The slider crank

Determine the angular velocity (ω_{AB})
the angular acceleration (α_{AB})
in terms of θ .

$$\frac{\sin \theta}{l} = \frac{\sin \beta}{r} \rightarrow \sin \beta = \frac{r}{l} \sin \theta$$

$$\cos \beta = \sqrt{1 - \frac{r^2}{l^2} \sin^2 \theta}$$

$$l \sin \beta = r \sin \theta$$

$$l \cos \beta \dot{\beta} = r \cos \theta \dot{\theta}$$

$$\omega_{AB} = \dot{\beta} = \frac{r \cos \theta \cdot \omega_0}{l \cdot \cos \beta} = \frac{r \cos \theta \cdot \omega_0}{l \cdot \sqrt{1 - \frac{r^2}{l^2} \sin^2 \theta}}$$

Ans.

$$l (-\sin \beta \cdot \ddot{\beta}) + l \cos \beta \ddot{\beta} = r (-\sin \theta \ddot{\theta}) + r \cos \theta \ddot{\theta}$$

α_{AB} $\because \omega_0 = \text{const}$

$$\alpha_{AB} = \ddot{\beta} = \frac{l \ddot{\beta} \sin \beta - r \ddot{\theta} \sin \theta}{l \cos \beta}$$

$$= \frac{\cancel{l} \cdot \frac{r^2 \cos^2 \theta \omega_0^2}{l^2 (1 - \frac{r^2}{l^2} \sin^2 \theta)} \sin \beta - r \omega_0^2 \sin \theta}{l \sqrt{1 - \frac{r^2}{l^2} \sin^2 \theta}}$$

$$= \frac{\frac{r^2 \cos^2 \theta \omega_0^2}{l (1 - \frac{r^2}{l^2} \sin^2 \theta)} \cdot \frac{r}{l} \sin \theta - r \omega_0^2 \sin \theta \cdot \frac{l}{l}}{l \sqrt{1 - \frac{r^2}{l^2} \sin^2 \theta}}$$

$$= \frac{r \omega_0^2 \sin \theta}{l} \cdot \frac{\frac{r^2 \cos^2 \theta}{l (1 - \frac{r^2}{l^2} \sin^2 \theta)} - l}{\sqrt{1 - \frac{r^2}{l^2} \sin^2 \theta}}$$

$$= \frac{r \omega_0^2 \sin \theta}{l} \cdot \frac{\frac{r^2}{l^2} \cos^2 \theta - 1 \cdot (1 - \frac{r^2}{l^2} \sin^2 \theta)}{(1 - \frac{r^2}{l^2} \sin^2 \theta)^{3/2}}$$

$$= \frac{r \omega_0^2 \sin \theta}{l} \cdot \frac{\frac{r^2}{l^2} - 1}{(1 - \frac{r^2}{l^2} \sin^2 \theta)^{3/2}}$$

Ans.